

New

Series CGZT three-jaw grippers with T-guide

Single and double acting, magnetic, self-centering Sizes: 40, 50, 64, 80, 100, 125, 160 mm







The new Series CGZT pneumatic grippers, thanks to the use of a high performing and precise force transmission system, are able to provide high gripping forces, while guaranteeing high repeatability in a compact and light design.

Available in 7 sizes (40, 50, 64, 80, 100, 125 and 160) and three different versions (double acting, single acting NO and single acting NC), allows you to find the best solution for every handling need. They are also available with a part retaining unit. This gripper series results particularly suitable to be combined with anthropomorphic or collaborative robots and gantry systems for applications in Pick and Place units, Material handling and the loading/unloading operations of machine tools.

- » Robust and light
- » 3 self-centering jaws
- » IP40
- » Fixing from the top and from below
- » Supply on the side or on the bottom (even without using tubes)
- » Double position detection
- » Variants available: for use in ATEX zones and for high temperatures
- » In compliance with **ROHS** directive
- » High positioning repeatability
- » High resistance and reliability to external loads thanks to T-guide
- » Free from Copper, PTFE and Silicone

GENERAL DATA

Type of construction Operation Sizes Force transmission Air connections	Three-jaw self-centering gripper with T-guide Single acting (NO, NC) double acting 40, 50, 64, 80, 100, 125, 160 mm Lever M3 (40), M5 (50, 64, 80), G1/8 (100, 125, 160)
Working pressure	2 ÷ 8 bar (double acting), 4 ÷ 8 bar (single acting)
Working temperature Store temperature	5°C ÷ 60°C (standard) - 5°C ÷ 130°C (high temperature version) -10°C ÷ 80°C
Maximum use frequency	5 Hz (40, 50, 64); 3 Hz (80); 2 Hz (100, 125); 1 Hz (160)
Repeatability	≤ 0.02 mm
Interchangeability	0.1 mm
Medium Lubrication	Air in class 7.4.4 according to ISO 8573-1. In case lubricated air is used, we recommend ISOVG32 oil and to never interrupt lubrication. After 10 million cycles, grease the sliding zones using Molykote DX grease.
Protection class Compatibility Certifications	IP40 ROHS Directive ATEX (II2G Ex h IIC T4 Gb II2D Ex h IIIC T120° Db -20°C≤Ta≤70°C). Add EX at the end of the commercial code to order the ATEX version.
Materials	Free from Copper, PTFE and Silicone
NOTE: Pressurize the pneu	matic system gradually in order to avoid uncontrolled movements.

CODING EXAMPLE

CGZT	-	050	-	NC	-	W	EX
CGZT	SERIES						
050	SIZES: 040 = Ø25 050 = Ø33 064 = Ø43 080 = Ø54 100 = Ø76 125 = Ø96 160 = Ø125						
NC	FUNCTIONING: = double acting NO = single acting NC = single acting], normally open			PNEUMATIC SYMBOLS PNZ1 PNZ3 PNZ2	:	
W	VERSION: = standard W = high tempera	atures (130°C) - non magnetic					
EX	Add EX to order th	e certified ATEX version					

PNEUMATIC SYMBOLS

The pneumatic symbols which have been indicated in the CODING EXAMPLE are shown below.

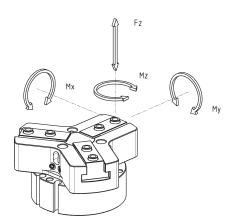






Maximum admissible loads and torques

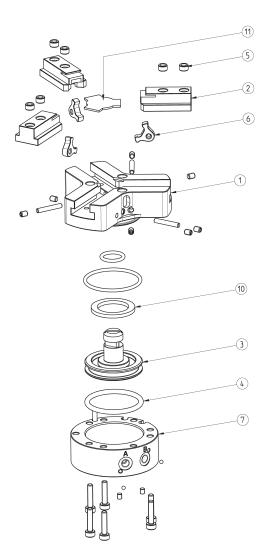
Fz s, Mx s, My s, Mz s = maximum admissible loads and torques in static conditions

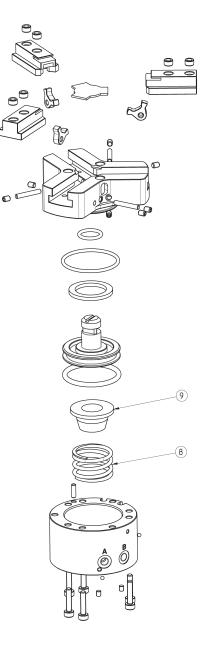


Mod.	Fz s (N)	Mx s (Nm)	My s (Nm)	Mz s (Nm)
CGZT-040	200	2.5	4	2.8
CGZT-050	400	7	7.3	7.7
CGZT-064	600	13	14	14
CGZT-080	1000	26	27	24
CGZT-100	1500	58	65	65
CGZT-125	2500	100	120	120
CGZT-160	4000	230	250	250

CAMOZZI Automation

Series CGPT gripper - construction





LIST OF COMPONENTS	
PARTS	MATERIALS
1 - Body	Aluminium
2 - Jaw	Stainless steel
3 - Piston	Stainless steel
4 - Seals	HNBR / FKM
5 - Centering bushes	Stainless steel
6 - Levers	Steel
7 - End cover	Aluminium
8 - Spring	Steel
9 - Guide de ressort	Aluminium
10 - Magnet	Neodymium
11 - Cover	Stainless steel

Products designed for industrial applications. General terms and conditions for sale are available on www.camozzi.com.

CGZT gripper, size 40mm - dimensions

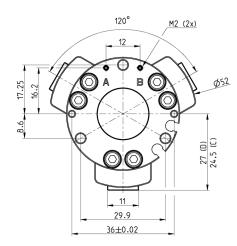


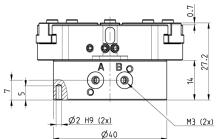
- DRAWING LEGEND:

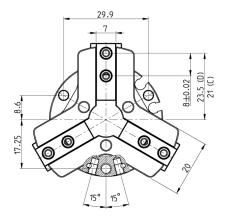
HANDLING AND VACUUM 2021/06

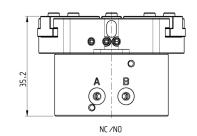
- DRAWING LEGEND: A = Opening of air connection B = Closing of air connection C = Closed gripper D = Open gripper

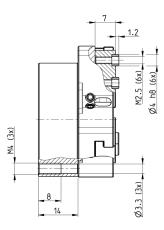












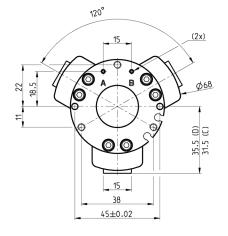
Mod.	Closing gripping force 1	fotal closing gripping	Opening gripping force T	otal opening grippin	g Stroke per	Working	Working I	Repeatability	/ Opening	Closing	J Weight
	each jaw at 6 bar (N)	force at 6 bar (N)	each jaw at 6 bar (N)	force at 6 bar (N)	jaw (mm)	pressure (bar)	temperature (°C)	(mm)	T (ms)	T (ms)	(Kg)
CGZT-040	60	181	67	202	2.5	2 ÷ 8	5 ÷ 60	≤ 0.02	57	63	0.114
CGZT-040-NC	93	80	33	100	2.5	4 ÷ 8	5 ÷ 60	≤ 0.02	56	106	0.132
CGZT-040-NO	27	280	100	300	2.5	4 ÷ 8	5 ÷ 60	≤ 0.02	79	49	0.130

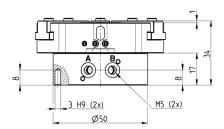


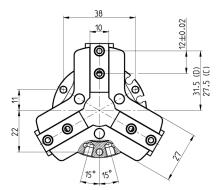
CGZT gripper, size 50mm - dimensions

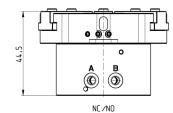


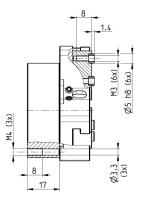












Mod.	Closing gripping force 1	fotal closing gripping	Opening gripping force	Total opening gripping	g Stroke per	Working	Working	Repeatability	, Opening	Closing) Weight
	each jaw at 6 bar (N)	force at 6 bar (N)	each jaw at 6 bar (N)	force at 6 bar (N)	jaw (mm)	pressure (bar)	temperature (°C)	(mm)	T (ms)	T (ms)	(Kg)
CGZT-050	115	346	130	390	4	2 ÷ 8	5 ÷ 60	≤ 0.02	75	85	0.240
CGZT-050-NC	160	480	83	250	4	4 ÷ 8	5 ÷ 60	≤ 0.02	56	151	0.280
CGZT-050-NO	70	210	173	520	4	4 ÷ 8	5 ÷ 60	≤ 0.02	137	55	0.275

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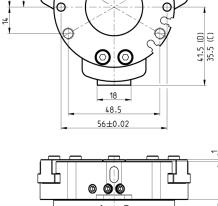
CGZT gripper, size 64mm - dimensions



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- DRAWING LEGEND:

- DRAWING LEGEND: A = Opening of air connection B = Closing of air connection C = Closed gripper D = Open gripper



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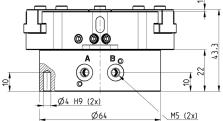
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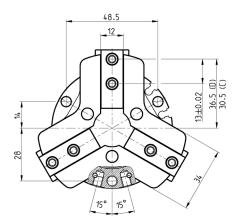
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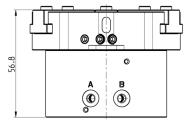
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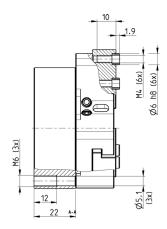
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NC /NO



Mod.	Closing gripping force 1	fotal closing gripping	Opening gripping force 1	otal opening gripping	g Stroke per	Working	Working F	Repeatabilit	y Opening	Closing	Weight
	each jaw at 6 bar (N)	force at 6 bar (N)	each jaw at 6 bar (N)	force at 6 bar (N)	jaw (mm)	pressure (bar)	temperature (°C)	(mm)	T (ms)	T (ms)	(Kg)
CGZT-064	223	670	242	726	6	2 ÷ 8	5 ÷ 60	≤ 0.02	85	104	0.461
CGZT-064-NC	320	960	147	440	6	4 ÷ 8	5 ÷ 60	≤ 0.02	88	158	0.560
CGZT-064-NO	127	380	323	970	6	4 ÷ 8	5 ÷ 60	≤ 0.02	153	71	0.537

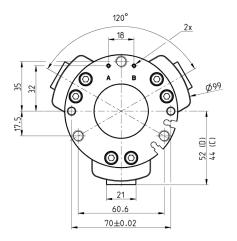


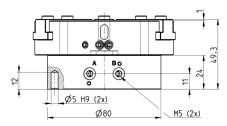
CGZT gripper, size 80mm - dimensions

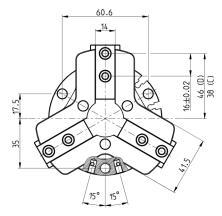


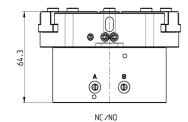
DRAWING LEGEND:

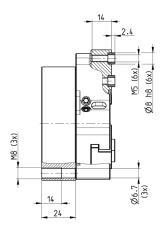
- DRAWING LEGEND: A = Opening of air connection B = Closing of air connection C = Closed gripper D = Open gripper











Mod.	Closing gripping force 1	otal closing gripping	Opening gripping force	fotal opening gripping	g Stroke per	Working	Working	Repeatabilit	y Opening	Closing	Weight
	each jaw at 6 bar (N)	force at 6 bar (N)	each jaw at 6 bar (N)	force at 6 bar (N)	jaw (mm)	pressure (bar)) temperature (°C)	(mm)	T (ms)	T (ms)	(Kg)
CGZT-080	327	980	359	1078	8	2 ÷ 8	5 ÷ 60	≤ 0.02	116	133	0.796
CGZT-080-NC	437	1310	247	740	8	4 ÷ 8	5 ÷ 60	≤ 0.02	88	258	0.987
CGZT-080-NO	213	640	450	1350	8	4 ÷ 8	5 ÷ 60	≤ 0.02	195	73	0.934

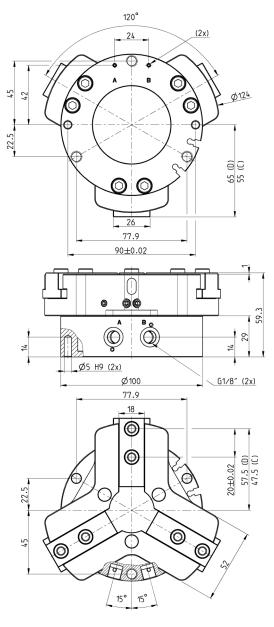
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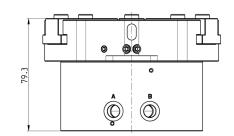
CGZT gripper, size 100mm - dimensions



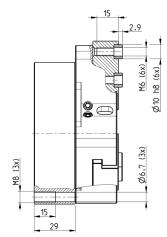


- A = Opening of air connection B = Closing of air connection C = Closed gripper
- D = Open gripper





NC /NO



Mod.			Opening gripping force 1					Repeatabilit			
	each jaw at 6 bar (N)	force at 6 bar (N)	each jaw at 6 bar (N)	force at 6 bar (N)	jaw (mm)	pressure (bar)	temperature (°C)	(mm)	T (ms)	T (ms)	(Kg)
CGZT-100	677	2030	722	2165	10	2 ÷ 8	5 ÷ 60	≤ 0.02	135	155	1.483
CGZT-100-NC	873	2620	523	1570	10	4 ÷ 8	5 ÷ 60	≤ 0.02	74	254	1.790
CGZT-100-NO	480	1440	917	2750	10	4 ÷ 8	5 ÷ 60	≤ 0.02	282	75	1.755

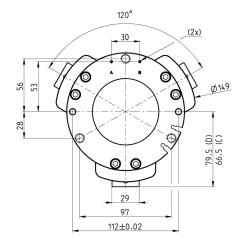


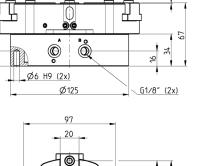
CGZT gripper, size 125mm - dimensions

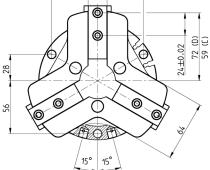
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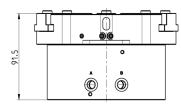




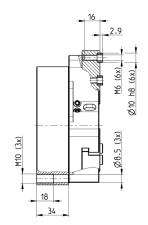








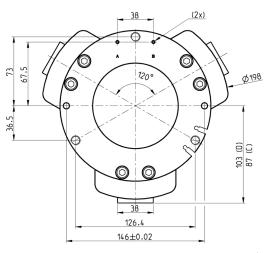
NC /NO

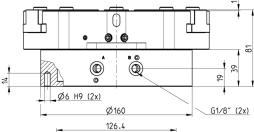


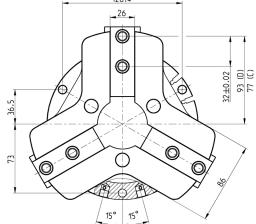
Mod.	Closing gripping force 1	fotal closing gripping	Opening gripping force 1	fotal opening gripping	g Stroke per	Working	Working	Repeatability	, Opening	Closing	Weight
	each jaw at 6 bar (N)	force at 6 bar (N)	each jaw at 6 bar (N)	force at 6 bar (N)	jaw (mm)	pressure (bar)	temperature (°C)	(mm)	T (ms)	T (ms)	(Kg)
CGZT-125	1123	3370	1198	3594	13	2 ÷ 8	5 ÷ 60	≤ 0.02	198	227	2.220
CGZT-125-NC	1400	4200	920	2760	13	4 ÷ 8	5 ÷ 60	≤ 0.02	108	349	3.005
CGZT-125-NO	843	2530	1477	4430	13	4 ÷ 8	5 ÷ 60	≤ 0.02	329	119	2.752

CGZT gripper, size 160mm - dimensions







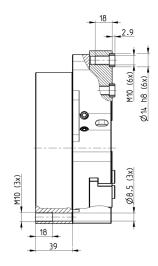


DRAWING LEGEND:

D = Open gripper

A = Opening of air connection B = Closing of air connection C = Closed gripper

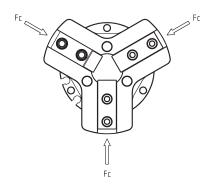


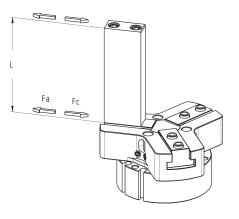


Mod.	Closing gripping force 1	fotal closing gripping	Opening gripping force 1	rotal opening grippin	g Stroke per	Working	Working	Repeatability	/ Opening	Closing	Weight
	each jaw at 6 bar (N)	force at 6 bar (N)	each jaw at 6 bar (N)	force at 6 bar (N)	jaw (mm)	pressure (bar)	temperature (°C)	(mm)	T (ms)	T (ms)	(Kg)
CGZT-160	1927	5780	1767	5300	16	2 ÷ 8	5 ÷ 60	≤ 0.02	239	304	4.714
CGZT-160-NC	2150	6450	1540	4620	16	4 ÷ 8	5 ÷ 60	≤ 0.02	150	791	6.504
CGZT-160-NO	1380	4140	2310	6930	16	4 ÷ 8	5 ÷ 60	≤ 0.02	418	129	5.851

SERIES CGZT THREE-JAW GRIPPERS WITH T-GUIDE

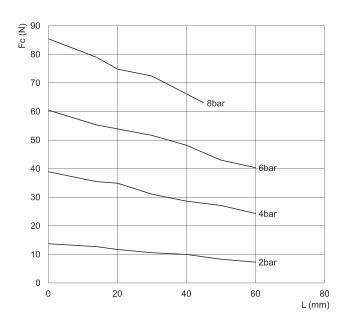
GRIPPING FORCE PER SINGLE JAW





The total gripping force has to be calculated as follows: Total Fc = Fc x 3 Total Fa = Fa x 3

Fc = closing gripping force Fa = opening gripping force L = gripping point length



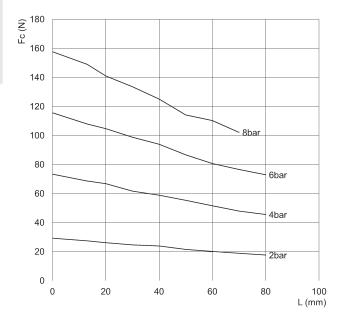
CGZT-040

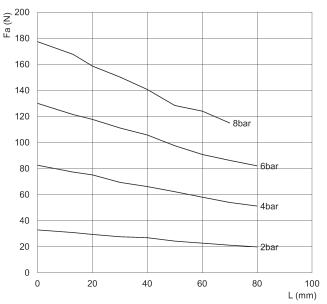
Fc = closing gripping force L = gripping point length () 2 120 120 100 80 8bar 60 6bar 40 4bar 20 2bar 0 0 20 40 60 80 L (mm)

CGZT-040

Fa = opening gripping force L = gripping point length

GRIPPING FORCE PER SINGLE JAW



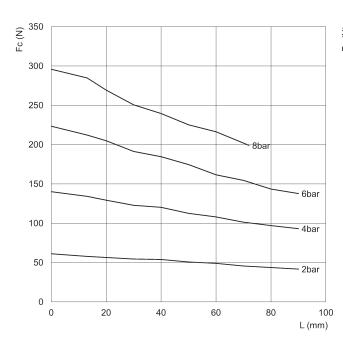


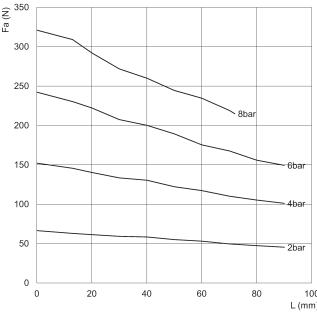
CGZT-050

Fc = closing gripping force L = gripping point length



Fa = opening gripping force L = gripping point length





CGZT-064

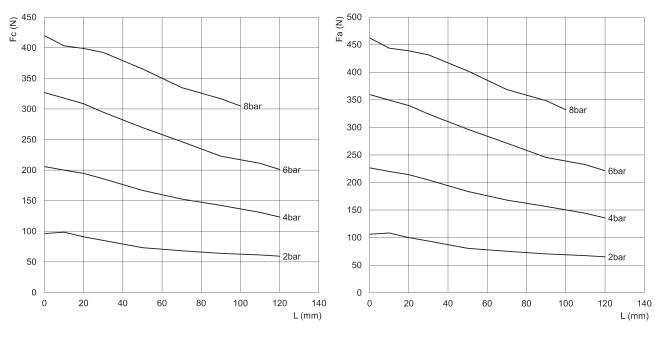
Fc = closing gripping force L = gripping point length

CGZT-064

100 L (mm) Fa = opening gripping force L = gripping point length

SERIES CGZT THREE-JAW GRIPPERS WITH T-GUIDE

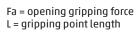
GRIPPING FORCE PER SINGLE JAW

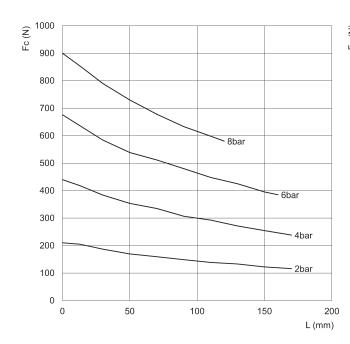


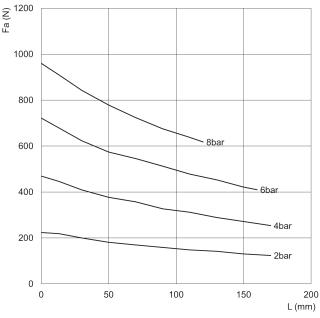
CGZT-080

CGZT-080

Fc = closing gripping force L = gripping point length





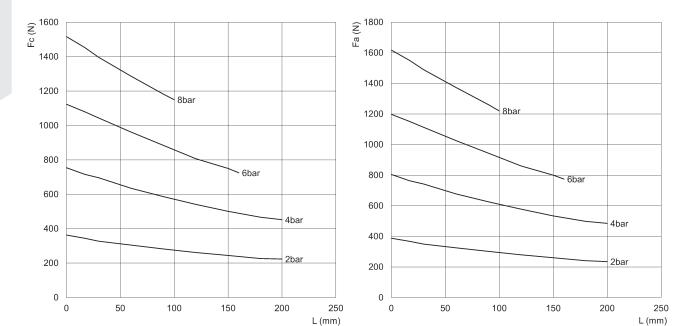


CGZT-100

Fc = closing gripping force L = gripping point length CGZT-100

Fa = opening gripping force L = gripping point length

GRIPPING FORCE PER SINGLE JAW

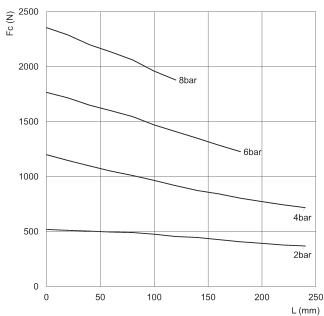


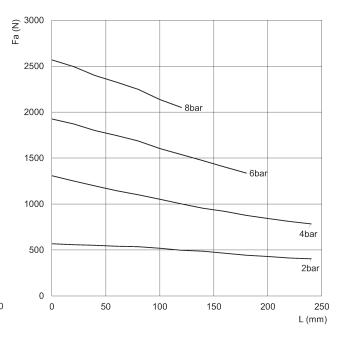
CGZT-125

Fc = closing gripping force L = gripping point length



Fa = opening gripping force L = gripping point length





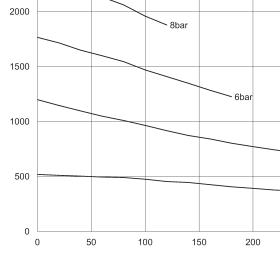
CGZT-160

Fc = closing gripping force L = gripping point length

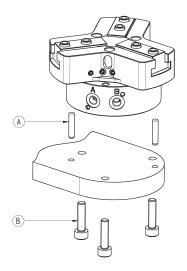
CGZT-160

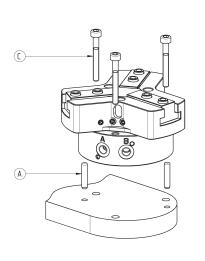
Fa = opening gripping force L = gripping point length

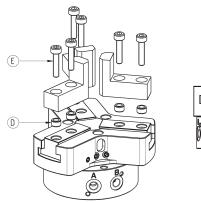
Automation

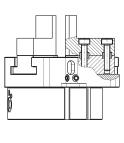


Examples of mounting



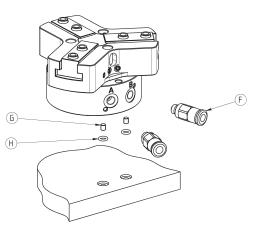






Mod.	А	В	С	D	E
CGZT-040	Ø2	M4	M3	Ø4	M2.5
CGZT-050	Ø3	M4	M3	Ø5	M3
CGZT-064	Ø4	M6	M5	Ø6	M4
CGZT-080	Ø5	M8	M6	Ø8	M5
CGZT-100	Ø5	M8	M6	Ø10	M6
CGZT-125	Ø6	M10	M8	Ø10	M6
CGZT-160	Ø6	M10	M8	Ø14	M10

Air supply ports



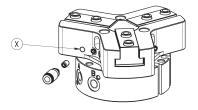
F	G	Н
M3	M2	OR 1x2.5
M5	M2.5	OR 1x3
M5	M3	OR 1x3.5
M5	M3	OR 1x3.5
G1/8	M3	OR 1x3.5
G1/8	M3	OR 1x3.5
G1/8	M4	OR 1x4.5
	M3 M5 M5 M5 G1/8 G1/8	M3 M2 M5 M2.5 M5 M3 M5 M3 G1/8 M3 G1/8 M3

Example of use of the pressurization/lubrication hole

Example of use of the lubrication (greasing) or pressurization hole of the zone with moving items

NOTE 1: grease the sliding zones using Molykote DX grease.

NOTE 2: supply a pressure of max 1 bar in order to avoid the sudden ejection of grease.





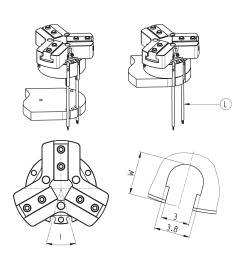
Mod.	Х	
CGZT-040	M3	
CGZT-050	M3	
CGZT-064	M5	
CGZT-080	M5	
CGZT-100	M5	
CGZT-125	M5	
CGZT-160	М5	

Example of mounting: sensors

L = sensor Series CSD

In order to position the sensor correctly, a channel must be created in the base.

Mod.	I	W
CGZT-040	32°	4.5
CGZT-050	30°	4.6
CGZT-064	30°	6.5
CGZT-080	32°	8.7
CGZT-100	28°	9.3
CGZT-125	24°	11.5
CGZT-160	20°	12.5

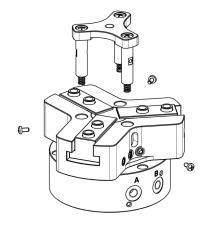


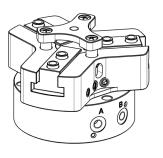
Automatio

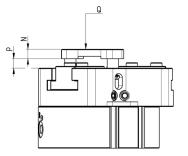


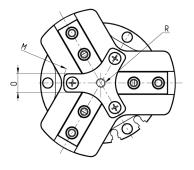
Part retaining unit











Mod.	М	Ν	0	Р	Q	R
P-CGZT-040	Ø24	3.5	6	0 ÷ 2.5	10 N	M3
P-CGZT-050	Ø32.5	4.5	8	0 ÷ 3	14 N	M4
P-CGZT-064	Ø39.5	5	10	0 ÷ 5	21 N	M5
P-CGZT-080	Ø49	6	12.5	0 ÷ 5	32 N	M6
P-CGZT-100	Ø59	7	14	0 ÷ 5	48 N	M8
P-CGZT-125	Ø73	8	18	0 ÷ 6	85 N	M10
P-CGZT-160	Ø99	9.5	25	0 ÷ 6	185 N	M10

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